A Constrained K-Means and Nearest Neighbor Approach for Route Optimization in the Bale Collection Problem

David Zamar<sup>1</sup> Bhushan Gopaluni<sup>1</sup> Shahab Sokhansanj<sup>1,2</sup>

<sup>1</sup>Department of Chemical and Biological Engineering, University of British Columbia

<sup>2</sup>Resource and Engineering Systems Group, Environmental Sciences Division, Oak Ridge National Laboratory, TN

20th World Congress of the International Federation of Automatic Control, 9-14 July 2017



**IFAC 2017** 

a place of mind THE UNIVERSITY OF BRITISH COLUMBIA







- The agricultural industry is now able to collect comprehensive real-time data regarding field operations.
- Novel algorithms and methodologies are needed to make proper use of this data.
- These techniques can be used to improve the coordination of agricultural machines and vehicles.

・ 同 ト ・ ヨ ト ・ ヨ ト …

- The agricultural industry is now able to collect comprehensive real-time data regarding field operations.
- Novel algorithms and methodologies are needed to make proper use of this data.
- These techniques can be used to improve the coordination of agricultural machines and vehicles.

- The agricultural industry is now able to collect comprehensive real-time data regarding field operations.
- Novel algorithms and methodologies are needed to make proper use of this data.
- These techniques can be used to improve the coordination of agricultural machines and vehicles.

**IFAC 2017** 

- Major field operations require the planned coordination of various farm equipment.
- The bale collection problem (BCP) appears after harvest and baling operations of a crop and consists of defining the sequence in which bales spread over a field are collected.

- Major field operations require the planned coordination of various farm equipment.
- The bale collection problem (BCP) appears after harvest and baling operations of a crop and consists of defining the sequence in which bales spread over a field are collected.

### Problem Description and Motivation

IFAC 2017



- The BCP is concerned with the collaborative operation of loaders and wagons.
- Planned management is required to coordinate the tasks efficiently.
- Collection strategy is typically based on the skills and experience of the operator.
- Inconsistent and subjective nature of decisions based on operator judgment tend to produce suboptimal solutions (Milkman et al., 2009).

ヘロト ヘワト ヘビト ヘビト

- The BCP is concerned with the collaborative operation of loaders and wagons.
- Planned management is required to coordinate the tasks efficiently.
- Collection strategy is typically based on the skills and experience of the operator.
- Inconsistent and subjective nature of decisions based on operator judgment tend to produce suboptimal solutions (Milkman et al., 2009).

ヘロン 不通 とくほ とくほう

- The BCP is concerned with the collaborative operation of loaders and wagons.
- Planned management is required to coordinate the tasks efficiently.
- Collection strategy is typically based on the skills and experience of the operator.
- Inconsistent and subjective nature of decisions based on operator judgment tend to produce suboptimal solutions (Milkman et al., 2009).

ヘロト ヘアト ヘビト ヘビト

- The BCP is concerned with the collaborative operation of loaders and wagons.
- Planned management is required to coordinate the tasks efficiently.
- Collection strategy is typically based on the skills and experience of the operator.
- Inconsistent and subjective nature of decisions based on operator judgment tend to produce suboptimal solutions (Milkman et al., 2009).

・ 同 ト ・ ヨ ト ・ ヨ ト …

### • More efficient bale collection plans are achievable.

- Utilize geo-positioning technology that make it possible to know the exact location of bales and machinery on the field (Amiama et al., 2008).
- We develop optimization models of the BCP, which can be easily integrated into farm management decision support systems.

・ 通 ト ・ ヨ ト ・ ヨ ト

**IFAC 2017** 

- More efficient bale collection plans are achievable.
- Utilize geo-positioning technology that make it possible to know the exact location of bales and machinery on the field (Amiama et al., 2008).
- We develop optimization models of the BCP, which can be easily integrated into farm management decision support systems.

・ 同 ト ・ ヨ ト ・ ヨ ト …

- More efficient bale collection plans are achievable.
- Utilize geo-positioning technology that make it possible to know the exact location of bales and machinery on the field (Amiama et al., 2008).
- We develop optimization models of the BCP, which can be easily integrated into farm management decision support systems.

・ 同 ト ・ ヨ ト ・ ヨ ト

- Solving the BCP involves identifying:
  - The optimal number and locations of roadside storage sites.
  - The bale collection routes that minimize the total travel distance.

・ 回 ト ・ ヨ ト ・ ヨ ト

- The identification of roadside storage sites where bales are to be transported can be expressed as a cluster analysis problem.
- The aim is to partition the bales into *k* clusters in which each bale belongs to the cluster with the nearest mean, resulting in a partition of the bales on the field.

- The identification of roadside storage sites where bales are to be transported can be expressed as a cluster analysis problem.
- The aim is to partition the bales into *k* clusters in which each bale belongs to the cluster with the nearest mean, resulting in a partition of the bales on the field.

- If the location of the cluster centers were not constrained to lie on the roadside, then the *k*-means algorithm (Hartigan, 1975), may be directly applied.
- Even so, the problem is NP-hard.
- The fact that the storage sites are constrained to lie on the roadside makes this part of the BCP an even greater challenge to solve.

- If the location of the cluster centers were not constrained to lie on the roadside, then the *k*-means algorithm (Hartigan, 1975), may be directly applied.
- Even so, the problem is NP-hard.
- The fact that the storage sites are constrained to lie on the roadside makes this part of the BCP an even greater challenge to solve.

- If the location of the cluster centers were not constrained to lie on the roadside, then the *k*-means algorithm (Hartigan, 1975), may be directly applied.
- Even so, the problem is NP-hard.
- The fact that the storage sites are constrained to lie on the roadside makes this part of the BCP an even greater challenge to solve.

- Given a set of points X = (x<sub>1</sub>, x<sub>2</sub>,..., x<sub>n</sub>), where each point is a *d*-dimensional real vector, *k*-means clustering aims to partition these *n* points into k ≤ n sets S = {S<sub>1</sub>, S<sub>2</sub>,..., S<sub>k</sub>} so as to minimize the within-cluster sum of squares.
- In the BCP, each point x<sub>i</sub> represents a bale's 2-dimensional field location coordinates.

- Given a set of points X = (x<sub>1</sub>, x<sub>2</sub>,..., x<sub>n</sub>), where each point is a *d*-dimensional real vector, *k*-means clustering aims to partition these *n* points into k ≤ n sets S = {S<sub>1</sub>, S<sub>2</sub>,..., S<sub>k</sub>} so as to minimize the within-cluster sum of squares.
- In the BCP, each point *x<sub>i</sub>* represents a bale's 2-dimensional field location coordinates.

We also have *m* compact sets in ℝ<sup>2</sup> denoted {*T*<sub>1</sub>,...,*T<sub>m</sub>*}, such that the valid positions for the cluster centers are in *T* = *T*<sub>1</sub> ∪ ··· ∪ *T<sub>m</sub>*.

• Define the auxiliary functions:

$$g_j(x) = \min_{t \in T_j} ||x - t||^2, \ j = 1, \dots, m$$

that calculate the minimum Euclidean distance between a given point, x, and any point in the set  $T_i$ .

- We also have *m* compact sets in ℝ<sup>2</sup> denoted {*T*<sub>1</sub>,...,*T<sub>m</sub>*}, such that the valid positions for the cluster centers are in *T* = *T*<sub>1</sub> ∪ ··· ∪ *T<sub>m</sub>*.
- Define the auxiliary functions:

$$g_j(\mathbf{x}) = \min_{t \in T_j} ||\mathbf{x} - t||^2, \ j = 1, \dots, m$$

that calculate the minimum Euclidean distance between a given point, x, and any point in the set  $T_j$ .

## Part I: Constrained Cluster Analysis of Bales *Optimization Problem*

$$\min_{(\mu_1, S_1), \dots, (\mu_k, S_k)} \sum_{i=1}^k \sum_{x \in S_i} ||x - u_i||^2$$
(1a)

subject to 
$$\prod_{j=1}^{m} g_j(\boldsymbol{u}_i) = 0 \quad \text{for } i = 1, \dots, k \quad (1b)$$
$$S_1 \cup S_2 \cup \dots \cup S_k = S \quad (1c)$$
$$S_i \cap S_j = \emptyset \quad \forall i \neq j. \quad (1d)$$

イロト 不得 とくほと くほとう

ъ

IFAC 2017

### Part I: Constrained Cluster Analysis of Bales

#### Optimization Algorithm

- Step 1 Choose k random points from S to be the initial cluster centers,  $u = (u_1, u_2, \dots, u_k)$ . The relaxed solution of the k-means algorithm is a good initial starting point.
- Step 2 For i = 1, ..., k, assign points to clusters based on their Euclidean distance to the cluster centers:

$$S_i = \left\{ x \in \mathcal{X} : ||x - u_i||^2 < ||x - u_j||^2, \ j \neq i \right\}.$$

Step 3 For i = 1, ..., k, update the cluster centers by solving the following minimization problem:

$$u_i = \arg\min_{\nu} \left\{ f_i(\nu) = \sum_{\mathbf{x} \in S_i} ||\mathbf{x} - \nu||^2 + \gamma \cdot g_i(\nu) \right\}$$

Step 4 Repeat Steps 2 and 3 until there is no significant change in the clustering criteria,  $\sum_{i=1}^{k} f_i(u_i)$ .

(日)

э

## Part I: Constrained Cluster Analysis of Bales Example of a constrained cluster analysis problem



- This part of the BCP may be formulated as a graph theory problem.
- For a given cluster, S<sub>α</sub>, α = 1,...,k, let G = (N<sub>α</sub>, A<sub>α</sub>) be an undirected graph, where N<sub>α</sub> is the set of nodes (bales) and A<sub>α</sub> is the set of edges.
- N<sub>α</sub> = {0, 1, ..., n<sub>α</sub>} is an index set for cluster S<sub>α</sub>, containing n<sub>α</sub> bales and a roadside storage node, denoted by 0.
- A<sub>α</sub> = {(i,j) | i,j ∈ N<sub>α</sub>; i < j} represents the set of (n<sub>α</sub> + 1)(n<sub>α</sub> + 2)/2 existing edges connecting the n<sub>α</sub> bales and the storage site.

ヘロン 人間 とくほ とくほ とう

э

- This part of the BCP may be formulated as a graph theory problem.
- For a given cluster,  $S_{\alpha}$ ,  $\alpha = 1, ..., k$ , let  $G = (N_{\alpha}, A_{\alpha})$  be an undirected graph, where  $N_{\alpha}$  is the set of nodes (bales) and  $A_{\alpha}$  is the set of edges.
- N<sub>α</sub> = {0, 1, ..., n<sub>α</sub>} is an index set for cluster S<sub>α</sub>, containing n<sub>α</sub> bales and a roadside storage node, denoted by 0.
- A<sub>α</sub> = {(i,j) | i,j ∈ N<sub>α</sub>; i < j} represents the set of (n<sub>α</sub> + 1)(n<sub>α</sub> + 2)/2 existing edges connecting the n<sub>α</sub> bales and the storage site.

ヘロト 人間 とくほとく ほとう

ъ

- This part of the BCP may be formulated as a graph theory problem.
- For a given cluster,  $S_{\alpha}$ ,  $\alpha = 1, ..., k$ , let  $G = (N_{\alpha}, A_{\alpha})$  be an undirected graph, where  $N_{\alpha}$  is the set of nodes (bales) and  $A_{\alpha}$  is the set of edges.
- N<sub>α</sub> = {0, 1, ..., n<sub>α</sub>} is an index set for cluster S<sub>α</sub>, containing n<sub>α</sub> bales and a roadside storage node, denoted by 0.
- A<sub>α</sub> = {(i,j) | i,j ∈ N<sub>α</sub>; i < j} represents the set of (n<sub>α</sub> + 1)(n<sub>α</sub> + 2)/2 existing edges connecting the n<sub>α</sub> bales and the storage site.

・ロト ・ 同ト ・ ヨト ・ ヨト … ヨ

- This part of the BCP may be formulated as a graph theory problem.
- For a given cluster,  $S_{\alpha}$ ,  $\alpha = 1, ..., k$ , let  $G = (N_{\alpha}, A_{\alpha})$  be an undirected graph, where  $N_{\alpha}$  is the set of nodes (bales) and  $A_{\alpha}$  is the set of edges.
- N<sub>α</sub> = {0,1,...,n<sub>α</sub>} is an index set for cluster S<sub>α</sub>, containing n<sub>α</sub> bales and a roadside storage node, denoted by 0.
- A<sub>α</sub> = {(i,j) | i,j ∈ N<sub>α</sub>; i < j} represents the set of (n<sub>α</sub> + 1)(n<sub>α</sub> + 2)/2 existing edges connecting the n<sub>α</sub> bales and the storage site.

・ロト ・ 同ト ・ ヨト ・ ヨト … ヨ

- The problem is to determine the set of routes that minimize the total travel distance within each cluster identified by the CCA algorithm.
- May be represented as a capacitated vehicle routing problem (CVRP).

ヘロト 人間 ト ヘヨト ヘヨト

- The problem is to determine the set of routes that minimize the total travel distance within each cluster identified by the CCA algorithm.
- May be represented as a capacitated vehicle routing problem (CVRP).

・ 同 ト ・ ヨ ト ・ ヨ ト …

# • A weight, $q_i$ , is assigned to each bale $i, 1 \le i \le n_{\alpha}$ ( $q_0 = 0$ ).

- Each edge has an associated cost, c<sub>ij</sub> > 0, of sending a vehicle from node *i* to node *j*.
- The c<sub>ij</sub> are assumed to be symmetric and proportional to the Euclidean distance, d<sub>ij</sub>, between any two nodes, thus c<sub>ij</sub> = c<sub>ji</sub> ∝ d<sub>ij</sub>, i, j ∈ N<sub>α</sub>.
- The collection activities are to be implemented by a fleet of v vehicles, v ≥ 1, with equal capacity, κ ≥ max{q<sub>i</sub> | 1 ≤ i ≤ n<sub>α</sub>}.

ヘロン 人間 とくほ とくほ とう

- A weight,  $q_i$ , is assigned to each bale  $i, 1 \le i \le n_{\alpha}$  ( $q_0 = 0$ ).
- Each edge has an associated cost,  $c_{ij} > 0$ , of sending a vehicle from node *i* to node *j*.
- The c<sub>ij</sub> are assumed to be symmetric and proportional to the Euclidean distance, d<sub>ij</sub>, between any two nodes, thus c<sub>ij</sub> = c<sub>ji</sub> ∝ d<sub>ij</sub>, i, j ∈ N<sub>α</sub>.
- The collection activities are to be implemented by a fleet of v vehicles, v ≥ 1, with equal capacity, κ ≥ max{q<sub>i</sub> | 1 ≤ i ≤ n<sub>α</sub>}.

ヘロン 人間 とくほ とくほとう

- A weight,  $q_i$ , is assigned to each bale  $i, 1 \le i \le n_{\alpha}$  ( $q_0 = 0$ ).
- Each edge has an associated cost, c<sub>ij</sub> > 0, of sending a vehicle from node *i* to node *j*.
- The c<sub>ij</sub> are assumed to be symmetric and proportional to the Euclidean distance, d<sub>ij</sub>, between any two nodes, thus c<sub>ij</sub> = c<sub>ji</sub> ∝ d<sub>ij</sub>, i, j ∈ N<sub>α</sub>.
- The collection activities are to be implemented by a fleet of v vehicles, v ≥ 1, with equal capacity, κ ≥ max{q<sub>i</sub> | 1 ≤ i ≤ n<sub>α</sub>}.

・ロト ・ 同ト ・ ヨト ・ ヨト … ヨ
- A weight,  $q_i$ , is assigned to each bale  $i, 1 \le i \le n_{\alpha}$  ( $q_0 = 0$ ).
- Each edge has an associated cost, c<sub>ij</sub> > 0, of sending a vehicle from node *i* to node *j*.
- The c<sub>ij</sub> are assumed to be symmetric and proportional to the Euclidean distance, d<sub>ij</sub>, between any two nodes, thus c<sub>ij</sub> = c<sub>ji</sub> ∝ d<sub>ij</sub>, i, j ∈ N<sub>α</sub>.
- The collection activities are to be implemented by a fleet of v vehicles, v ≥ 1, with equal capacity, κ ≥ max{q<sub>i</sub> | 1 ≤ i ≤ n<sub>α</sub>}.

イロト イポト イヨト イヨト 三日

1) all routes begin and end at the roadside storage node

- 2) no two routes visit the same bale
- 3) all bales are visited exactly once
- 4) no vehicle can be loaded exceeding its maximum capacity

- 1) all routes begin and end at the roadside storage node
- 2) no two routes visit the same bale
- 3) all bales are visited exactly once
- 4) no vehicle can be loaded exceeding its maximum capacity

- 1) all routes begin and end at the roadside storage node
- 2) no two routes visit the same bale
- 3) all bales are visited exactly once
- 4) no vehicle can be loaded exceeding its maximum capacity

(4回) (日) (日)

- 1) all routes begin and end at the roadside storage node
- 2) no two routes visit the same bale
- 3) all bales are visited exactly once

4) no vehicle can be loaded exceeding its maximum capacity

- 1) all routes begin and end at the roadside storage node
- 2) no two routes visit the same bale
- 3) all bales are visited exactly once
- 4) no vehicle can be loaded exceeding its maximum capacity

- Decision vector is  $x = (x_{ijr})$ , where  $i, j \in N_{\alpha}$ , and  $r \in R = \{1, 2, \dots, \tau\}$
- τ = [n<sub>α</sub>/κ] is the number of routes needed in order to pick up all of the n<sub>α</sub> bales:

$$x_{ijr} = \begin{cases} 1 & \text{if route } r \text{ contains edge } (i,j) \\ 0 & \text{otherwise,} \end{cases}$$

ヘロト ヘアト ヘビト ヘビト

- Decision vector is  $x = (x_{ijr})$ , where  $i, j \in N_{\alpha}$ , and  $r \in R = \{1, 2, \dots, \tau\}$
- $\tau = \lceil n_{\alpha}/\kappa \rceil$  is the number of routes needed in order to pick up all of the  $n_{\alpha}$  bales:

$$x_{ijr} = \begin{cases} 1 & \text{if route } r \text{ contains edge } (i,j) \\ 0 & \text{otherwise,} \end{cases}$$
(2)

《曰》《圖》《臣》《臣》 三臣

### Part II: Within Cluster Route Optimization Optimization Problem – Mathematical Representation

**IFAC 2017** 

$$\begin{array}{ll} \underset{u}{\mathsf{minimize}} & \sum_{r \in R}^{t} \sum_{(i,j) \in A_{\alpha}} c_{ij} x_{ijr} & (3a) \\ \\ \mathsf{subject to} & \sum_{r \in R} \sum_{j \in N_{\alpha}} x_{ijr} = 1 & \forall i \in N_{\alpha} & (3b) \\ \\ & \sum_{i \in N_{\alpha}} \sum_{j \in N_{\alpha}} x_{ijr} \times q_{j} \leq \kappa & \forall r \in R & (3c) \\ \\ & \sum_{j \in N_{\alpha}} x_{0jr} = 1 & \forall r \in R & (3d) \\ \\ & \sum_{i \in N_{\alpha}} x_{ijr} = \sum_{i \in N_{\alpha}} x_{jir} & \forall j \in N_{\alpha}, r \in R & (3e) \end{array}$$

### Part II: Within Cluster Route Optimization

#### Min-min min-max route optimization algorithm (MMROA)

Step 1 Set  $k = \min(\kappa, |N_{\alpha}| - 1)$ , where  $\kappa$  is the capacity of the wagon. Compute the set of k - 1 nearest neighbors for each bale  $b \in N_{\alpha}$ . Denote the set of k-1 nearest neighbors of bale b as  $O_{k}$ . Step 2 Define the function  $M(x, S_{\alpha}) = \begin{cases} 1 & \text{if } x \in S_{\alpha} \\ 0 & \text{otherwise} \end{cases}$ For each bale,  $b \in N_{\alpha}$ , compute  $m_b = \sum_{i \in N_{\infty}} M(b, Q_i)$ Let  $b_1^* = \arg\min_{b} \{m_b : b \in N_\alpha\}$ and  $b_2^* = \arg\max\{m_b : b \in N_\alpha\}.$ Randomly choose  $b_1^*$  or  $b_2^*$  with equal probability. Denote the chosen bale as  $b^*$ . Step 3 Among the sets  $\mathcal{Q} = \{ \mathcal{O}_h \mid b^* \in \mathcal{O}_h, b \in N_{\alpha} \},\$ which contain  $b^*$  select the one that has the shortest cycle, including the roadside storage node, and denote this set as  $O^*$ . Step 4 Update the set  $N_{\alpha}$  by:  $N_{\alpha} = N_{\alpha} \setminus O^*$ . If  $N_{\alpha} \neq \emptyset$ , then go to Step 1.

## Part I: Constrained Cluster Analysis of Bales Example Problem



Obtained tours by the MMROA for a problem previously proposed by Grisso et al. (2007). MMROA yields an additional 6.8% reduction in the total travel distance.

- We consider a study area of size  $4800 \text{ m} \times 4800 \text{ m}$  that is composed of 9 equal-sized sections of 256 ha each.
- Bales are spatially distributed across the field according to a Poisson process and assuming a uniform yield.
- Four different wagon capacities are considered (8, 15, 30, and 70).
- Based on an analysis of the within-cluster sum of squares, the bales have been divided into five clusters.

- We consider a study area of size  $4800 \text{ m} \times 4800 \text{ m}$  that is composed of 9 equal-sized sections of 256 ha each.
- Bales are spatially distributed across the field according to a Poisson process and assuming a uniform yield.
- Four different wagon capacities are considered (8, 15, 30, and 70).
- Based on an analysis of the within-cluster sum of squares, the bales have been divided into five clusters.

- We consider a study area of size  $4800 \text{ m} \times 4800 \text{ m}$  that is composed of 9 equal-sized sections of 256 ha each.
- Bales are spatially distributed across the field according to a Poisson process and assuming a uniform yield.
- Four different wagon capacities are considered (8, 15, 30, and 70).
- Based on an analysis of the within-cluster sum of squares, the bales have been divided into five clusters.

- We consider a study area of size  $4800 \text{ m} \times 4800 \text{ m}$  that is composed of 9 equal-sized sections of 256 ha each.
- Bales are spatially distributed across the field according to a Poisson process and assuming a uniform yield.
- Four different wagon capacities are considered (8, 15, 30, and 70).
- Based on an analysis of the within-cluster sum of squares, the bales have been divided into five clusters.

# Study Problem Description



24/30

ъ

⇒ + ⇒

### Study Problem Constrained Cluster Analysis

IFAC 2017



ъ

⇒ < ≥</p>

### Study Problem MMROA solutions for wagon capacities of (a) 8 and (b) 15 bales





(a) Wagon capacity of 8 bales. (b) Wagon capacity of 15 bales.

**IFAC 2017** 

### Study Problem MMROA solutions for wagon capacities of (a) 35 and (b) 70 bales





(c) Wagon capacity of 35 bales. (d) Wagon capacity of 70 bales.

#### **MMROA Solutions**

Wagon Capacity (bales)	Number of Routes	Distance (m)
8	229	525,692
15	124	345,755
35	55	225,206
70	30	184,546

ヘロト 人間 とくほとくほとう

ъ

- The potential benefits of our approach to solving the BCP are its scalability and ease of implementation.
- Developed a constrained *k*-means algorithm and nearest neighbor approach to the BCP, which minimizes travel distance and hence fuel consumption.
- Able to tackle large problems and can be easily incorporated into existing bale collection operations.

- The potential benefits of our approach to solving the BCP are its scalability and ease of implementation.
- Developed a constrained *k*-means algorithm and nearest neighbor approach to the BCP, which minimizes travel distance and hence fuel consumption.
- Able to tackle large problems and can be easily incorporated into existing bale collection operations.

- The potential benefits of our approach to solving the BCP are its scalability and ease of implementation.
- Developed a constrained *k*-means algorithm and nearest neighbor approach to the BCP, which minimizes travel distance and hence fuel consumption.
- Able to tackle large problems and can be easily incorporated into existing bale collection operations.

- C. Amiama, J. Bueno, C. J. Álvarez, and J. M. Pereira. Design and field test of an automatic data acquisition system in a self-propelled forage harvester. *Computers and Electronics in Agriculture*, 61(2):192–200, 2008.
- R. D. Grisso, J. S. Cundiff, and D. H. Vaughan. Investigating Machinery Management Parameters with Computer Tools. ASABE Conf, Paper 071030, 2007.
- J. A. Hartigan. Clustering algorithms. John Wiley & Sons, New York, 1975.
- K. L. Milkman, D. Chugh, and M. H. Bazerman. How Can Decision Making Be Improved? Perspectives on Psychological Science, 4(4):379–383, 2009.

イロト 不得 とくほ とくほとう

ъ