

Data Visualization for Large-Scale, Industrial Model Predictive Controllers

Siang Lim, Shams Elnawawi, Daniel O'Connor, Bhushan Gopaluni.

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Visualization tools for multivariable controllers

Overview:

- Large, multivariable controllers can be difficult to understand and troubleshoot.
- Existing tools in industry rely on awkward, static, tabular views. <u>Can we do better?</u>
- Yes! In a 2022 CEP paper, we show that interactive heatmaps can help.



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Interactive visualization for diagnosis of industrial Model Predictive Controllers with steady-state optimizers

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I work on Model Predictive Controllers (MPCs)

- All controllers force a system to follow a desired behavior by adjusting actuators (valves, pumps, steering wheel etc.)
- PID control uses just the current and past states of the system to adjust the actuator. <u>No predictive ability.</u>





(a) The PID knows only what has happened and adjusts the controller based on the measured error.

Hoekstra et al. Critical Care (2009) and Lindberg, MSc Thesis, Chalmers (2014)

More to

the left

PID

Model Predictive Controllers (MPCs)

- All controllers force a system to follow a desired behavior by adjusting actuators (valves, pumps, steering wheel etc.)
- PID control uses just the current and past states of the system to adjust the actuator. No predictive ability.
- MPC tries to predict future states using current and past states, and a model of the system.
- Good models -> Good MPC controller



fMore to the right

Too slow



(b) The MPC follows its model and the present measured value. If the model is good (green car, in the middle) it follows the setpoint well, but a small error in the model can lead the system astray (orange and blue car, on the sides).

Hoekstra et al. Critical Care (2009) and Lindberg, MSc Thesis, Chalmers (2014)

The model: steady-state gain matrix in MPCs

The model describes relationships between MVs and CVs. At steadystate: the model is a <u>gain matrix</u>

MV: manipulated variable CV: controlled variable

$$G = \begin{bmatrix} 0.1942 & -0.0029 \\ 0.1843 & -0.0288 \end{bmatrix} \frac{\text{CV1}}{\text{CV2}}$$

Example:

If MV1 goes up by 1 unit, then:

- CV1 goes down by -0.1942
- CV2 goes up by 0.1843

Steady-state Gain Matrix



Problems with industrial MPC controllers

"MPC math is simple and elegant; MPC engineering is not."

https://www.emersonautomationexperts.com/papers/MPC-Unsustainable-benefits.pdf



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Problem 1 (Model):

Large MPC gain matrices are complex and hard to visualize!

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Problem 1 (Model):

Large MPC gain matrices are complex and hard to visualize!

Problem 2 (Real-time Monitoring):

Multivariable MPC time series are complex and hard to visualize!

Problem 1: Large model gain matrices are complex





Toy Model: 2x2

Problem 1: Large model gain matrices are complex



Actual Controllers: 44x64

- Why it's bad: Tedious to navigate, filter and identify relationships. e.g. If MV1 goes up... what happens to the CVs?
- **It gets worse:** Not even the full 44x64 matrix... could also be much bigger elsewhere
- The question: Can we do better than static tables? How?

Problem 2: Classical MPC time series trends are complex

- 4 lines for each MPC variable
 - Upper Limit
 - Lower Limit
 - Measurement
 - SS Target
- Variables can be constrained (at limits) or unconstrained.
- Too many variables! Typically spread out across multiple pages due to limited screen space



UI limitations: Can't <u>easily</u> put variables of interest on the same page, need to click on different pages



Fault diagnosis for MPCs is tedious, here's why:



OPERATOR CALLS: WHY DID MPC DROP OUR PRODUCTION RATE?!! I don't know... let's find out!



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OPERATOR CALLS: WHY DID MPC DROP OUR PRODUCTION RATE?!! I don't know... let's find out!



1. What was this MV controlling? Which CVs is it connected to?

	A	в	с	D	E	F	G	н	1	J	к	L	м	Ν	0	Р	Q	R	s	т
		52TAR	52TAR	52A122	918F1	108.CO	522112	263.CO	52FC161BI	52AIR	1CALC	52PDR	52PDR	52TXS	52TXS	52PDR208	52FR2	525121	52PR2	52FC2
1		126	1153	8F5	0	т	4.COT	F	AS	BAL	0	263F	264F	701	707	F	00F	00.COT	101B	7
2	52FC126.SP	1	0	-0.91	-21.5	-4.14	0	0	-0.01528	0	0	0	-0.28	13.8	10.21	0.11482	2.357	7.418	2.927	29.4
3	52TC1153.SP	0	1	-0.02	-0.58	-0.15	0	0.614	0	0	0	-0.04	-0.02	0.436	0.3	0.0144	0.101	0.838	0.257	3.32
4	52FC124.SP	0	0	4.176	145	72.5	60.07	5.394	0.936071	1	0	0	0	-63.2	-29	-1.392	0	0	0	
5	52FC171.CO	0	0	0.072	2.5	1.25	0	0.093	0	-0.02	1.901	0	0	-1.09	-0.5	-0.024	0	0	0	
6	52PDC108.SP	0	0	0	0	-11	1.106	6.937	-0.01775	0	2.375	-0.81	1.04	0	0	0.07633	0	0	0	
7	52HC102	0	0	0	0	0	0	0.166	. 0	0	0	-0.02	0	2.412	0	0.04846	0	0	0	
8	52FC121.SP	0	0	-0.03	-0.67	0	0	0.407	0	0	0	0	0	-1.81	-1.81	0.01662	0.847	0	0	
9	52HC266.CO	0	0	-0.03	-0.61	0	0	0.373	0	0	0	0	0	-1.66	-1.66	0.02908	0.777	0	0	
10	60FR153B.PWL	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
11	52PC111A.SP	0	0	0	0	-7.58	0.763	0	-0.01224	0	1.638	0	0	0	0	0	0	0	0	
12	52TC104.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
13	52FC1127.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
14	52FC1144.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
15	52FC1143.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
16	52FC1129.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
17	52FC135.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
18	52FC132.CO	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
19	52FC130.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
20	52FC1130.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
21	52HC174.CCT4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
22	52FC154.CCT4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
23	52FC232.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
24	52FC133.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-0.0
25	52FC106.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	19.7
26	52FC137.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-0.0
27	52PC113.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0.211	0	-2.5
28	52FC136.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
29	52PC114A.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
30	52FC317.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
31	52FC138.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
32	52TC107.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
33	52FI1159	0	0	-0	0	-0	0.002	-0.01	-1.53E-05	0	0	6E-04	-0	0.024	0.02	0	0.002	0.007	0.003	0.03
34	52TR252	0	0	0	0	0	0.208	0	0	0	0.401	0	0	0	0	0	0	0	0	0.40
35	53FC128	0	0	3E-04	0.006	0	0	-0	0	0	0	0	0	0	0	-5.73E-05	2E-04	0	0	



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1. What was this MV controlling? Which CVs is it connected to?

	A	в	С	D	E	F	G	н	1	J	к	L	м	N	0	Р	Q	R	s	т					
		STAR	SZTAR	574122	918F1	108.00	527112	263.00	52EC161BI	SZAIR	10410	52008	52008	SZTES	52735	52202208	52ER2	525121	52982	525(23					
1		126	1153	8F5	0	т	4.COT	F	AS	BAL	0	263F	264F	701	707	F	OOF	00.COT	101B	7					
2	52FC126.SP	1	0	-0.91	-21.5	-4.14	0	0	-0.01528	0	0	0	-0.28	13.8	10.21	0.11482	2.357	7.418	2.927	29.44	_				
3	52TC1153.SP	0	1	-0.02	-0.58	-0.15	0	0.614	0	0	0	-0.04	-0.02	0.436	0.3	0.0144	0.101	0.838	0.257	3.325					
4	52FC124.SP	0	0	4.176	145	72.5	60.07	5.394	0.936071	1	0	0	0	-63.2	-29	-1.392	0	0	0	0	2		r of	C	1
5	52FC171.CO	0	0	0.072	2.5	1.25	0	0.093	0	-0.02	1.901	0	0	-1.09	-0.5	-0.024	0	0	0	0	 .	LOOP	λaι	υv	1
6	52PDC108.SP	0	0	0	0	-11	1.106	6.937	-0.01775	0	2.375	-0.81	1.04	0	0	0.07633	0	0	0	0					
7	52HC102	0	0	0	0	0	0	0.166	0	0	0	-0.02	0	2.412	0	0.04846	0	0	0	0					
8	52FC121.SP	0	0	-0.03	-0.67	0	0	0.407	0	0	0	0	0	-1.81	-1.81	0.01662	0.847	0	0	0					
9	52HC266.CO	0	0	-0.03	-0.61	0	0	0.373	0	0	0	0	0	-1.66	-1.66	0.02908	0.777	0	0	0					
10	60FR153B.PWL	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
11	52PC111A.SP	0	0	0	0	-7.58	0.763	0	-0.01224	0	1.638	0	0	0	0	0	0	0	0	0					
12	52TC104.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
13	52FC1127.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
14	52FC1144.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
15	52FC1143.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
16	52FC1129.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
17	52FC135.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
18	52FC132.CO	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
19	52FC130.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
20	52FC1130.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
21	52HC174.CCT4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
22	52FC154.CCT4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
23	52FC232.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
24	52FC133.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-0.03					
25	52FC106.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	19.79					
26	52FC137.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-0.04					
27	52PC113.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0.211	0	-2.55					
28	52FC136.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
29	52PC114A.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
30	52FC317.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
31	52FC138.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
32	52TC107.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0					
33	52FI1159	0	0	-0	0	-0	0.002	-0.01	-1.53E-05	0	0	6E-04	-0	0.024	0.02	0	0.002	0.007	0.003	0.033					
34	52TR252	0	0	0	0	0	0.208	0	0	0	0.401	0	0	0	0	0	0	0	0	0.402					
35	53FC128	0	0	3E-04	0.006	0	0	-0	0	0	0	0	0	0	0	-5.73E-05	2E-04	0	0	0					









MPC diagnosis issues

Troubleshooting MPC problems takes hours/days

- Root cause of faults usually not obvious
- Need to trend the right variables <u>on the same page</u>, but we have 100+ variables, which ones are the 'right' ones to trend? Can't trend all at the same time.

Strong reliance on process knowledge

- Time series trends don't mean much to less experienced engineers:
 - just squiggly lines with no context (speaking from personal experience)
 - new engineers wouldn't know if a MV/CV should be typically constrained/unconstrained

	A	в	с	D	E	F	G	н	1	J	к	L	м	N	0	Р	Q	R	s	т					
1	1	52TAR 126	52TAR 1153	52AI22 8F5	918F1 0	108.CO T	522112 4.COT	263.CO	S2FC161BI AS	S2AJR BAL	1CALC O	52PDR 263F	52PDR 264F	52TXS 701	52TXS 707	S2PDR208	52FR2 00F	525I21 00.CDT	52PR2 1018	52FC	13			_	
2	52FC126.SP	1	0	-0.91	-21.5	-4.14	0	0	-0.01528	0	0	0	-0.28	13.8	10.21	0.11482	2.357	7,418	2.927	29.4	4				IDC
3	52TC1153.SP	0	1	-0.02	-0.58	-0.15	0	0.614	0	0	0	-0.04	-0.02	0.436	0.3	0.0144	0.101	0.838	0.257	3.32	5				JBC
4	52FC124.SP	0	0	4.176	145	72.5	60.07	5.394	0.936071	1	. 0	0	0	-63.2	-29	-1.392	0	0	0		0				
5	52FC171.CO	0	0	0.072	2.5	1.25	0	0.093	0	-0.02	1.901	0	0	-1.09	-0.5	-0.024	0	0	0		0				
6	52PDC108.SP	0	0	0	0	-11	1.106	6.937	-0.01775	0	2.375	-0.81	1.04	0	0	0.07633	0	0	0		0				
7	52HC102	0	0	0	0	0	0	0.166	0	0	0	-0.02	0	2.412	0	0.04846	0	0	0		0				
8	52FC121.SP	0	0	-0.03	-0.67	0	0	0.407	0	0	0	0	0	-1.81	-1.81	0.01662	0.847	0	0		0				
9	52HC266.CO	0	0	-0.03	-0.61	0	0	0.373	0	0	0	0	0	-1.66	-1.66	0.02908	0.777	0	0		0				
10	60FR1538.PWL	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0				\checkmark
11	52PC111A.SP	0	0	0	0	-7.58	0.763	0	-0.01224	0	1.638	0	0	0	0	0	0	0	0		0				$\mathbf{\tilde{\mathbf{v}}}$
12	52TC104.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0				
13	52FC1127.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0				
14	52FC1144.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0				
15	52FC1143.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0				
16	52FC1129.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0				
17	52FC135.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0				
18	52FC132.CO	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0				
19	52FC130.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0				
20	52FC1130.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0				
21	52HC174.CCT4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0	A Deal	F		Refresh Data
22	52FC154.CCT4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		۵ 🔚				
23	52FC232.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0	-		HCC to GHT, B	JPD
24	52FC133.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-0.0	3		н		3000.00
25	52FC106.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	19.7	9		ы	<u> </u>	
26	52FC137.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-0.0	14			55	650.00
27	52PC113.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0.211	0	-2.5	5	-	Ħ.	u	400.00
28	52FC136.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0	415.051	Ы	52FC1143 SP	650.00
29	52PC114A.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0	1.12.42	-	<u> </u>	
30	52FC317.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0	T	ы	HCC to DHT, B	20
31	52FC138.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0	\mathbf{k}	H	UL.	2000.00
32	52TC107.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0	1	И		987.77
33	52FI1159	0	0	-0	0	-0	0.002	-0.01	-1.53E-05	0	0	6E-04	-0	0.024	0.02	0	0.002	0.007	0.003	0.03	3	Nu	11		
34	52TR252	0	0	0	0	0	0.208	0	0	0	0.401	0	0	0	0	0	0	0	0	0.40	12	1			0.00
35	53FC128	0	0	3E-04	0.006	0	0	-0	0	0	0	0	0	0	0	-5.73E-05	2E-04	0	0		0 322	4:15:05	ρį.	52FC1144.SP	947.67
					253	1			0						~			-					Ţ	Frac O/H Term	p.F
					۱٣	٣٩		٦r	r	$ \mathcal{A} $		Λ		4	-	M.	M	v	V	K	\sim	1	1	UL	255.00
					24	4		-V-		1	~		\square	-	-				+	+	-	- 1	Н	55	255.00
					25		6.04 (94)			I, I			24.024								10000		J.		204.00
					41	8/2022 4 1	5.05 PW				_	et c	24.001	iours <	210					4/15	V2022	4:15:05 /	-	521C104.5P	254.99
					50	×		-	-		-	-		-	-				-	-		-	Н	LGO Draw, Br	6000.00
								-								+ +	-	-		+	-	-	2		3603.00
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					15	8/2022 4 1	5:05 PM					6.6	24.00	tours <	⊳a.					4/19	2022	4:15:05		52FC135.5P	3310.25
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Seems like a gap! Took initiative to find visualization solutions

My thoughts:

- I just want very simple improvements :
 - the ability to easily plot time series on the same page
 - an easy way to navigate through the model.



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- APC has been around in refining since 1980s and matured in the 1990s.
 - Surely someone out there must have a better solution by now?

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Existing Visualization Tools

Simple Solutions:

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 - an easy way to navigate through the model.
- APC has been around in refining since 1980s and matured in the 1990s.
 - Surely someone out there must have a better solution by now?
- Only one solution found in literature -Honeywell Elucidator (2002).





Idea 1: cut down visual noise in gain matrix with a heatmap

	A	в	с	D	Ε	F	G	н	1	J	к	L	м	Ν	0	Р	Q	R	s	т	U	v	w
1		52TAR 126	52TAR 1153	52AI22 8F5	918F1 0	108.CO T	522112 4.COT	263.CO F	52FC161BI AS	52AIR BAL	1CALC O	52PDR 263F	52PDR 264F	52TXS 701	52TXS 707	52PDR208 F	52FR2 00F	525I21 00.COT	52PR2 1018	52FC23 7	MDUT	52LCC9 OHCC	HCC9
2	52FC126.SP	1	. 0	-0.91	-21.5	-4.14	0	0	-0.01528	0	0	0	-0.28	13.8	10.21	0.11482	2.357	7.418	2.927	29.44	25.99	-7.44	-17.
3	52TC1153.SP	0	1	-0.02	-0.58	-0.15	0	0.614	0	0	0	-0.04	-0.02	0.436	0.3	0.0144	0.101	0.838	0.257	3.325	2.935	0	
4	52FC124.SP	0	0	4.176	145	72.5	60.07	5.394	0.936071	1	0	0	0	-63.2	-29	-1.392	0	0	0	0	0	0	
5	52FC171.CO	0	0	0.072	2.5	1.25	0	0.093	0	-0.02	1.901	0	0	-1.09	-0.5	-0.024	0	0	0	0	0	0	
6	52PDC108.SP	0	0	0	0	-11	1.106	6.937	-0.01775	0	2.375	-0.81	1.04	0	0	0.07633	0	0	0	0	0	0	
7	52HC102	0	0	0	0	0	0	0.166	0	0	0	-0.02	0	2.412	0	0.04846	0	0	0	0	0	0	
8	52FC121.SP	0	0	-0.03	-0.67	0	0	0.407	0	0	0	0	0	-1.81	-1.81	0.01662	0.847	0	0	0	0	0	
9	52HC266.CO	0	0	-0.03	-0.61	0	0	0.373	0	0	0	0	0	-1.66	-1.66	0.02908	0.777	0	0	0	0	0	
10	60FR153B.PWL	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1.087	0	
11	52PC111A.SP	0	0	0	0	-7.58	0.763	0	-0.01224	0	1.638	0	0	0	0	0	0	0	0	0	0	-1.27	-2.0
12	52TC104.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1.633	2.60
13	52FC1127.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	2.513	
14	52FC1144.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0.05
15	52FC1143.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0.05
16	52FC1129.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0.004	0.00
17	52FC135.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
18	52FC132.CO	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0.203	0.32
19	52FC130.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	3.13	4.99
20	52FC1130.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
21	52HC174.CCT4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
22	52FC154.CCT4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
23	52FC232.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
24	52FC133.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-0.03	-0.03	0	
25	52FC106.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	19.79	17.47	0	
26	52FC137.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-0.04	-0.04	0	
27	52PC113.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0.211	0	-2.55	-2.25	0	
28	52FC136.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
29	52PC114A.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
30	52FC317.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
31	52FC138.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
32	52TC107.SP	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
33	52FI1159	0	0	-0	0	-0	0.002	-0.01	-1.53E-05	0	0	6E-04	-0	0.024	0.02	0	0.002	0.007	0.003	0.033	0.026	0	
34	52TR252	0	0	0	0	0	0.208	0	0	0	0.401	0	0	0	0	0	0	0	0	0.402	0.363	0	
35	53FC128	0	0	3E-04	0.006	0	0	-0	0	0	0	0	0	0	0	-5.73E-05	2E-04	0	0	0	0	0	0.00



- Gain directions are more important (from a user's perspective), rather than the actual value.
- For troubleshooting purposes, we just want to know movement direction (up or down?).
- Key insight: Maybe we don't need to show the actual numbers!

Idea 1: cut down visual noise in gain matrix with a heatmap



- Gain directions are more important (from a user's perspective), rather than the actual value.
- For troubleshooting purposes, we want to know movement direction (up or down?).
- Encoding directions as a heatmap helps reduce visual noise and cognitive load

Idea 1: cut down visual noise in gain matrix with a heatmap



Better than spreadsheets, but still a static heatmap with limited capabilities. Need something more interactive (filtering, zooming, sorting etc.)

Clustergrammer - visualizing high-dimensional biological data

i = README.md

clustergrammer

npm v1.19.5 license MIT

Clustergrammer is a web-based tool for visualizing high-dimensional data (e.g. a matrix) as an interactive and shareable hierarchically clustered heatmap. Clustergrammer's front end (Clustergrammer-JS) is built using D3.js and its back-end (Clustergrammer-PY) is built using Python. Clustergrammer produces highly interactive visualizations that enable intuitive exploration of high-dimensional data and has several biology-specific features (e.g. enrichment analysis, see Biology-Specific Features) to facilitate the exploration of gene-level biological data. Click the screenshot below to view an interactive tutorial:



Write a parser: controllers and models are plaintext files

CCF - controller configuration file

MDL –	controller	model	file
	controlici	mouci	me

	parser		backend config	frontend con
1702	.MOVACC~~LOCAL~~R4~~0,~~	95438	-8.834142e-002 -8.926429e-002 -9.018/1/e-002	-9.111005e-002 -9.203292e-002
1700	.MAXHUV~~~LUCAL~~~R4~~~100,~~~~ .MDLIND~~~CONSTANT~~~CH(12)~~~52FC317,SP~~~	95437	-8.372704e-002 -8.464992e-002 -8.557279e-002	2 -8.649567e-002 -8.741854e-002
1699	MANACT~~LOCAL~~I4~~0~~	95436	-7.91126/e-002 -8.003554e-002 -8.095842e-002	-8.188129e-002 -8.280417e-002
1698	.LVLIND~~LOCAL~~~R4~~~0.~~~	95435	-/.449829e-002 -/.542117e-002 -7.634404e-002	-/./26692e-002 -/.818979e-002
1698	.LPCRIT-~~LOCAL~~~I4~~~0~~~	95434	-6.988392e-002 -7.080679e-002 -7.172967e-002	-/.265254e-002 -/.357542e-002
1695	.LMVENG~~~WRITE~~~R4~~~800.~~~""::"1.51.2.1450.12":DBVL:	95433	-6.526954e-002 -6.619242e-002 -6.711529e-002	-6.80381/e-002 -6.896104e-002
1694	.LLINDM~~~RDWRT~~~R4~~~1200.~~~""::"1.31.9.421.19":DBVL:	95432	-6.065517e-002 -6.157804e-002 -6.250092e-002	-6.3423/9e-002 -6.43466/e-002
1693	.ISMET~~~CONSTANT~~~I4~~~0~~~	95431		
1691	.IREVRS~~~LUCAL~~~I4~~~0~~~ .ISEF~~~CONSTANT~~~I4~~~0~~~	95430	-5.1455500-002 -5.2552230-002 -5.3279020-002	-5.419504e-002 -5.511/92e-002
1690		95429	-4.0770200-002 -4.7719120-002 -4.0045520-002	-4.930900002 - 5.03020900002
1689	.INDFLG~~LOCAL~~I4~~~0~~~	05420		-4.0580000-002 $-5.050200-002$
1688	ENGIND CONSTANT COULD THE COULD TO THE COULD CONTRACT IN THE COULD	95427	-4 2081720-002 -4 3010710-002 -4 3070000-002	-4.400201e-002 -4.584828e-002
1686	DESCIND	95427	-3.728649e - 002 - 3.825792e - 002 - 3.920917e - 002	-4.017688e-002 $-4.112303e-002$
1685	.CST~~~WRITE~~~R4~~~.007~~""::"1.51.2.1441.12":DBVL:	95426	-3,246340e-002 -3,342404e-002 -3,440502e-002	-3.536027e-002 $-3.633461e-002$
1684	CSTIND LOCAL TAnna Base	95425	-2.749285e-002 -2.851865e-002 -2.950487e-002	-3.050697e-002 -3.147519e-002
1683	.CRIIND~~LOCAL~~14~~1~~	95424	-2.233948e-002 -2.336108e-002 -2.441595e-002	-2.543792e-002 -2.648430e-002
1681	.BARIU~~~LUCAL~~~R4~~~4000.~~~ CMOVaaaWPTTEaaaPdaaaa1.45200aaa.""***"1.51.2.1448.12"*DBV/*	95423	-1.726679e-002 -1.827875e-002 -1.926072e-002	-2,028711e-002 -2,129183e-002
1680	.BARISC~~LOCAL~~I4~~0~~	95422	-1.213147e-002 -1.316906e-002 -1.423902e-002	-1.525473e-002 -1.628569e-002
1679	.BARIL~~~LOCAL~~~R4~~~1000.~~~	95421	-7.222148e-003 -8.184575e-003 -9.108321e-003	-1.009051e-002 -1.107503e-002
1678	.AWSCOD~~LOCAL~~I4~~0~~	95420	-2.429630e-003 -3.312579e-003 -4.288900e-003	-5.264561e-003 -6.271625e-003
1670	.ATAG3~~~BUILD~~~CH(50)~~~30~~~	95419	3.926405e-005 -5.742692e-005 -3.851119e-004	-9.327383e-004 -1.608904e-003
1675	[IND:52FC317.SP]	95418	52FC317.sp DEBUT 0/H LI	-9.228751198254448e-004



UBC

Phase 1: Interactive MPC models with Clustergrammer



Adapted from Clustergrammer.js source code, with some custom-coded HTML5/CSS styling and D3.js charts







UBC

Time series data for each MPC variable spread across different pages, multiple views and trends, can we do better than this without 'squishing' the trends?



Time series data for each MPC variable spread across different pages, multiple views and trends, can we do better than this without 'squishing' the trends?

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X-axis: time

Time series data for each MPC variable spread across different pages, multiple views and trends, can we do better than this without 'squishing' the trends?



Time series data for each MPC variable spread across different pages, multiple views and trends, can we do better than this without 'squishing' the trends?

Dynamic Contraint Map (DCM) – compressed time series values into colors, based on active constraint status, multiple variables now visible on one single page

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Compressed time series as a Dynamic Constraint Map





Key insight for MPC diagnosis: most variables are irrelevant!



Many MV/CVs do not undergo any constraint (color) changes.

These MV/CVs would not have caused the

Key insight: We can hide these!

Hiding irrelevant variables reduces visual noise



Hide irrelevant variables with no constraint changes



- Hiding irrelevant variables allow us to focus on just the ones that directly contributed to the fault.
- Don't need to dig through pages of time series trends

Hiding irrelevant variables reduce visual noise





Revamped fault diagnosis process



Problem 2: Solved. Only plot constraints, ther filter by colors to hide irrelevant variables to quickly drill down to the root causes. UBC

Revamped fault diagnosis process







Problem 1: Solved. Clustergrammer for better user interface + smaller submatrix to explore using Dynamic Constraint Map filters.



Revamped fault diagnosis process







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